

Description

Circuit arrangement for electronically generating a ringing impedance

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The present invention relates to a circuit arrangement as claimed in the preamble of patent claim 1, as is known from US 5,485,516.

In analog telecommunications systems, in order  
10 to notify a subscriber of an incoming call, a ringing signal is transmitted to the terminal of the subscriber. This ringing signal takes the form of a sinusoidal alternating voltage, the so-called ringing voltage or ringing alternating voltage. The called  
15 subscriber terminal has to detect the ringing signal and when necessary react to the ringing signal (for example by notifying the called subscriber by means of a ringing tone or by connecting to the line). In order to adapt to the telephone line, subscriber terminals  
20 form ringing impedances which have to satisfy different requirements owing to the differing design of the telephone networks in different countries. In Germany, the ringing impedance requirements can be obtained from the requirement catalog of the Bundespost [German  
25 Federal postal service] BAPT 223 ZV5, issue 5.2.1994, page 12; chapter 2.6.1 Ringing Impedance.

In telephone terminals, ringing impedances are usually formed from a resistor and a capacitor, the resistor forming the resistive part, and the capacitor  
30 the capacitive part, of a ringing impedance. The values of the resistor and capacitor must be adapted here to the requirements for a particular country, which requirements prescribe specific values for the ringing impedance. Owing to these requirements, a telephone  
35 terminal must have a specific design for a particular country. The disadvantage here is

country. The disadvantage here is the increased expenditure on the production of subscriber terminals because a separate subscriber terminal variant which fulfils the ringing impedance requirements has to be  
5 manufactured for each country.

From US 5,485,516 it is known to make the line impedance of a telephone line adaptable to the line conditions, for example the transmission characteristics, by means of a transistor and a  
10 controller which controls this transistor. However, the ringing impedance is implemented here with a capacitor and a resistor, and both have to be adapted in a specific way for a particular country.

The invention is therefore based on the technical object of making available a circuit arrangement of the type mentioned at the beginning in which the ringing impedance can be adapted easily, and yet as flexibly as possible, to the given conditions by  
15 circuit means.

This objective is achieved according to the invention by means of a circuit arrangement having the features of patent claim 1.  
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Accordingly, a circuit arrangement of the type mentioned at the beginning is made available in which a  
25 controller is provided for setting the impedance, said controller adapting the ringing impedance to the given conditions and having a programmable digital filter, and it being possible to set the transmission function of the controller by programming the filter  
30 coefficients of the digital filter.

Advantageous refinements of the circuit arrangement emerge from the respective subclaims.

The controller according to the invention can be used to program the ringing impedance and thus adapt  
35 it to the respectively desired conditions, for example to a very wide range of different specific requirements for particular countries. For this purpose, the controller has a digital filter which can be programmed, for example, by means of a program-

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input voltage and whose output signal controls the transistor.

In a further preferred embodiment, a voltage divider divides the voltage present at the first output of the rectifier into a smaller voltage.

In a particularly preferred embodiment, the digital power inverter circuit, the digital filter and the digital rectifier circuit are integrated on one digital module.

In a preferred embodiment, the analog/digital converter, the digital/analog converter and the analog integrator circuit are integrated on one analog module.

In a further preferred embodiment, the controller has a first analog integrator circuit which is connected upstream of the control terminal of the first transistor and which integrates the difference between a first input voltage and a second input voltage and whose output signal controls the first transistor, and a second analog integrator circuit which is connected upstream of the control terminal of the second transistor and which integrates the difference between a third input voltage and a fourth input voltage and whose output signal controls the second transistor. This circuit arrangement advantageously has no need of a rectifier circuit for rectifying the ringing alternating voltage.

A first voltage divider preferably divides the first potential of the ringing alternating voltage, and a second voltage divider preferably divides the second potential of the ringing alternating voltage.

In one preferred embodiment, a first and a second analog/digital converter, a first and a second digital/analog converter and the first and second analog integrator circuits are integrated on one analog module.

In a preferred embodiment, the transistors are embodied as n-channel MOSFETs.

Further advantageous embodiments and developments of the invention can be found in the subclaims, the following description and the figures.

The invention is explained in more detail below  
5 by means of an advantageous exemplary embodiment which is given in the figures of the drawing, in which:

Fig. 1 shows a first exemplary embodiment of a circuit arrangement for electronically generating a ringing impedance;

10 Fig. 2 shows a timing diagram with a digital input signal and the digital output signal, calculated therefrom, of a digital power inverter circuit;

Fig. 3 shows a voltage-controlled power source for setting the conduction current according to figure 1;  
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Fig. 4 shows a second exemplary embodiment of a circuit arrangement for electronically generating a ringing impedance;

20 Fig. 5 shows two voltage-controlled power sources for setting a first and second conduction current according to figure 4.

In all the figures of the drawing, identical or functionally identical elements and signals are  
25 provided with identical reference symbols.

The circuit arrangement illustrated in fig. 1 for electronically generating a ringing impedance has two terminals a and b which can be connected to a two-wire line of a telephone network. Ringing signals can  
30 be received from another subscriber via the two-wire line, the ringing signals being generated by means of a sinusoidal alternating voltage  $V_{\sim}$  with the frequency  $f_R$ . This alternating voltage becomes the ringing alternating voltage below. The switch S, which  
35 corresponds to the hook switch, is open with the result that direct signal elements in the ringing signal are blocked by means of a capacitor C.

The capacitor C simultaneously forms a capacitive part of the ringing impedance. Connected

downstream of the capacitor C is a bridge rectifier 1 which rectifies the ringing alternating voltage. The following circuits are provided with voltage from the rectified ringing alternating voltage. Furthermore, the rectified ringing alternating voltage ensures the setting of the conduction current I which is used to set the ringing impedance. A rectified positive ringing alternating voltage Va or negative ringing alternating voltage Vb is applied to a first output 12 and a second output 13 of the bridge rectifier 1, respectively. The rectified positive ringing alternating voltage Va and negative ringing alternating voltage Vb are referred to a reference potential VSS, the amplitude of the rectified positive ringing alternating voltage Va being much greater than the amplitude of the rectified negative ringing alternating voltage Vb.

The first output 12 and second output 13 of the bridge rectifier 1 are connected to the reference potential VSS via a transistor T1 and a resistor R1, respectively. The transistor T1 forms, in combination with the capacitor C, the ringing impedance. The ringing impedance can be adapted to the various requirements which are specific to particular countries by controlling the resistance of the transistor T1. For this purpose, a control voltage VSt for the transistor T1 is derived from the rectified positive ringing alternating voltage Va and negative ringing alternating voltage Vb using a digital controller.

The rectified positive ringing alternating voltage Va, which has high voltage values, is divided into a smaller voltage by means of a voltage divider R2 and R3, in order to be processed by the following circuits in which signals have only low voltage levels in comparison with the rectified positive ringing alternating voltage.

The voltage-divided positive ringing alternating voltage Va and the negative ringing alternating voltage Vb are fed to a subtractor circuit 7 at whose output a difference voltage Vab is present.

The difference voltage  $V_{ab}$  is subsequently sampled by a first analog/digital converter 2 with a sampling rate  $f_s$  and converted into a digital signal  $V'_{ab}$ .

5           The digital signal  $V'_{ab}$  is fed to a first digital power inverter circuit 3. Figure 2 illustrates a timing diagram with the digital input and output signals of the digital power inverter circuit. If the digital values  $V'_{ab}$  drop below a lower predefinable threshold value MIN at the input of the first digital power inverter circuit 3, a counter begins to count with the sampling rate  $f_s/N$  of the digital signal. If the counter reading exceeds a predefinable value which can be set by a digital control device 10 in accordance with the frequency of the ringing alternating voltage, the digital values at the output  $V'_{ab\sim}$  of the first digital power inverter circuit 3 are inverted by reversing their sign after a waiting time  $T_S$  expires. During the waiting time  $T_S$ , the counter remains reset and does not begin to count again until the digital values  $V'_{ab}$  drop below the threshold value MIN at the input. A digital output signal, which constitutes a first ringing alternating voltage referred to the reference potential VSS, is thus generated from the digital input signal which constitutes a rectified sinusoidal oscillation - the ringing alternating voltage referred to the reference potential VSS.

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          The digital output signal of the digital power inverter circuit 3 is fed to a digital filter 4. For adaptation to specific requirements for particular countries, the digital filter 4 can be programmed by means of a digital control device 10 in order to be able to adapt the ringing impedance, and for this purpose it has a programmable transmission function  $k$ .

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For this purpose, the phase shift and amplification which are necessary for the ringing impedance are calculated from the input signal  $V'_{ab\sim}$  by means of the digital filter 4. The digital filter 4 can be embodied here as a digital hardware filter in which the

coefficients are programmable. The digital filter can likewise be embodied as a signal processing algorithm on a digital signal processor, the filter function being adjustable for various ringing impedances by means of variables.

A digital rectifier circuit 5 rectifies the digital output signal of the digital filter 4 VSI~ by forming absolute values.

The output signal VSI of the digital rectifier circuit 5 is converted into an analog signal VI by a digital/analog converter 6.

The analog signal VI is fed to a first input of an analog integrator circuit 8. The negative ringing alternating voltage Vb, which is proportional to the conduction current, is fed to the analog integrator circuit 8 via a second input. A difference, which is subsequently integrated, is formed in the analog integrator circuit 8 from the two input signals. The output signal VSt of the analog integrator circuit 8 is fed to the control terminal of the transistor T1. The transistor T1 is set by means of the supplied voltage VSt.

Figure 3 illustrates the adjustability of the conduction current I by means of the transistor T1. The analog signal VI of the digital controller and the negative ringing alternating voltage Vb, which is proportional to the conduction current, are fed to a subtractor circuit 21 at whose output the difference voltage VI - Vb is present. The difference voltage VI - Vb is integrated by an integrator circuit. The voltage VSt which is fed to the control terminal of the transistor T1 is present at the output of the integrator circuit 20. The conduction current I is set by means of the transistor T1. The integrator circuit 20 integrates the difference voltage VI - Vb until the difference voltage VI - Vb = 0. A conductance value  $GM = I/VI = 1/R1$  can be derived from this using  $Vb = R1 \cdot I = VI$ .



The conduction current I is thus controlled by means of the analog signal VI of the digital controller in such a way that the necessary ringing impedance Z is calculated for a difference voltage Vab from the amplification factor ksense of the voltage divider R2 and R3, the transmission function k of the digital filter 4 and the conductance value GM of the analog integrator circuit:

$$Z = \frac{Vab}{I} = \frac{1}{ksense \cdot k \cdot GM} = \frac{R1}{ksense} = f(k)$$

The conduction current I can thus be set by means of the transistor T1. The transistor T1 can in turn be set by means of the programmable transmission function k of the digital filter 4. The ringing impedance thus depends on the programmable transmission function k of the digital filter 4 and can be adapted to various specific requirements for particular countries by simply reprogramming the transmission function k of the digital filter 4. To do this, specific values for a particular country can be stored for the ringing impedance in a memory 11, for example. The digital control device 10 reads out of the memory 11 the values from the memory 11 which are necessary for programming a specific ringing impedance for a particular country, programs the digital filter 4 accordingly and sets the digital power inverter 3 to the frequency fR of the ringing alternating voltage.

The circuit arrangement illustrated in fig. 4 for electronically generating a ringing impedance has a first terminal a and a second terminal b which can be connected to a two-conductor subscriber line. Ringing signals can be received via the two-wire line, the ringing signals being generated by a sinusoidal alternating voltage V~ with a frequency fR. Direct signal elements in the ringing signal are blocked by means of a first capacitor C1 and a second capacitor C2.

The first capacitor C1 and the second capacitor C2 also form a capacitive part of a ringing impedance.

A first series circuit composed of the first capacitor C1, the load path of a first transistor T2 and a first resistor R10 is provided for the positive half-wave of the ringing alternating voltage  $V_{-}$ . The series circuit connects the first terminal a to a reference potential VSS. A first potential  $V_{a-}$  of the ringing alternating voltage  $V_{-}$  can be tapped at the connecting point of the first capacitor C1 and of the first transistor T2.

A second series circuit composed of the second capacitor C2, the load path of a second transistor T3 and a second resistor R20 is provided for the negative half-wave of the ringing alternating voltage  $V_{-}$ . The series circuit connects the second terminal b to the reference potential VSS. A second potential  $V_{b-}$  of the ringing alternating voltage  $V_{b-}$  can be tapped at the connecting point of the second capacitor C2 and of the second transistor T3.

The ringing impedance is formed in each case for the positive or negative half-wave of the ringing alternating voltage  $V_{-}$  by the first capacitor C1 and the first transistor T2 or the second capacitor C2 and the second transistor T3. To do this, a first conduction current I1 and a second conduction current I2 are respectively set in the first and second series circuits respectively.

For the positive half-wave, the second transistor T3 is connected with low impedance so that the second series circuit between the second terminal b and the reference potential VSS has low impedance. For the negative half-wave, the first transistor T2 is connected with low impedance, so that the first series circuit between the first terminal a and the reference potential VSS has low impedance.

The first potential  $V_{a-}$  (positive half-wave) is divided by a first voltage divider R30 and R50 into a

smaller voltage which is converted into a first digital signal V'a~ by a first analog/digital converter 2'.

The second potential Vb~ (negative half-wave) is divided by a second voltage divider R40 and R60 into a smaller voltage which is converted into a second digital signal V'b~ by a second analog/digital converter 2'.

The first digital signal V'a~ and the second digital signal V'b~ are fed to a digital filter 4 (impedance filter).

The digital filter 4 is programmed by a control unit 10 - for example a microprocessor - which is connected to a memory 11. The programming of the digital filter 4 serves here to set specific parameters of the ringing impedance for particular countries. To do this, different specific data for particular countries can be stored in the memory 11. Depending on the area of application of the circuit arrangement, the control unit 10 reads the specific data for a particular country out of the memory 11 and correspondingly programs the digital filter 4.

The digital filter 4 generates a first digital output signal VSI1 and a second digital output signal VSI2.

The first digital output signal VSI1 is converted by a first digital/analog converter 6' into a first input signal VI1 for a first analog integrator circuit 8'.

In parallel, the second digital output signal VSI2 is converted by a second digital/analog converter 6'' into a second input signal VI2 for a second analog integrator circuit 8''.

The first analog integrator circuit 8' integrates the difference between the first input signal VI1 and a second input signal Vam which is tapped at the connecting point of the load path of the first transistor T2 and of the first resistor R10. The second input signal  $Vam = R10 \cdot I1$  depends here on the first conduction current I1.

In parallel, the second analog integrator circuit 8'' integrates the difference between the first input signal VI2 and a second input signal Vbm which is tapped at the connecting point of the load path of the second transistor T3 and of the second resistor R20. The second input signal  $V_{bm} = R20 \cdot I2$  depends here on the second conduction current I2.

Figure 5 illustrates the design of the first and second analog integrator circuits and the adjustability of the first conduction current I1 and of the second conduction current I2 by means of the first transistor T2 or the second transistor T3.

The first analog control signal VI1 and the potential Vam, which is tapped at the connecting point of the load path of the first transistor T2 and of the first resistor R10, are fed to a first subtractor circuit 12 at whose output a difference voltage  $VI1 - V_{am}$  is present. The difference voltage  $VI1 - V_{am}$  is integrated by a first integrator circuit 11. A voltage VSt1 which is fed to the control terminal of the first transistor T2 is present at the output of the first integrator circuit 11. The first conduction current I1 is set by means of the first transistor T2. The first integrator circuit 11 integrates the difference voltage  $VI1 - V_{am}$  until the difference voltage  $VI1 - V_{am} = 0$ . A conductance value  $GM1 = I1/VI1 = 1/R10$  can be derived from this using  $V_{am} = R10 \cdot I1 = VI1$ .

The first conduction current I1 is thus controlled by means of the first analog signal VI1 of the digital controller in such a way that the necessary ringing impedance Z1, given a positive half-wave of the ringing alternating voltage  $V_{\sim}$ , is calculated from the amplification factor ksensel of the first voltage divider R30 and R50, a first transmission function k1 of the digital filter 4 and the conductance value GM1 of the first analog integrator circuit 8':

$$Z1 = \frac{V_{a \sim}}{I1} = \frac{1}{ksensel \cdot k1 \cdot GM1} = \frac{R10}{ksensel \cdot k1} = f_1(k1)$$

The first conduction current  $I_1$  can thus be set by means of the first transistor  $T_2$ . The first transistor  $T_2$  can in turn be set by means of the programmable first transmission function  $k_1$  of the digital filter 4. The ringing impedance thus depends on the programmable first transmission function  $k_1$  of the digital filter 4 and can be adapted to various specific requirements for particular countries by simply reprogramming the first transmission function  $k_1$  of the digital filter 4. To do this, specific values for the ringing impedance for particular countries can be stored in the memory 11, for example. The control device 10 reads out of the memory 11 the values which are necessary for programming a specific ringing impedance for a particular country and reprograms the first transmission function  $k_1$  of the digital filter 4 accordingly.

The second analog control signal  $VI_2$  and the potential  $V_{bm}$  which is tapped at the connecting point of the load path of the second transistor  $T_3$  and of the second resistor  $R_{20}$  are fed to a second subtractor circuit 22 at whose output a difference voltage  $VI_2 - V_{bm}$  is present. The difference voltage  $VI_2 - V_{bm}$  is integrated by a second integrator circuit 21. A voltage  $V_{St2}$  which is fed to the control terminal of the second transistor  $T_3$  is present at the output of the second integrator circuit 21. The second conduction current  $I_2$  is set by means of the second transistor  $T_3$ . The second integrator circuit 21 integrates the difference voltage  $VI_2 - V_{bm}$  until the difference voltage  $VI_2 - V_{bm} = 0$ . A conductance value  $GM_2 = I_2/VI_2 = 1/R_{20}$  can be derived from this using  $V_{bm} = R_{20} \cdot I_2 = VI_2$ .

The second conduction current  $I_2$  is thus controlled by means of the second analog signal  $VI_2$  of the digital controller in such a way that the necessary ringing impedance  $Z_2$ , given a negative half-wave of the ringing alternating voltage  $V_-$ , is calculated from the amplification factor  $ksense_2$  of the second voltage

divider R40 and R60, a second transmission function  $k_2$  of the digital filter 4 and the conductance value  $GM_2$  of the second analog integrator circuit 8'' as:

$$5 \quad Z_2 = \frac{V_b \sim}{I_2} = \frac{1}{k_{sense2} \cdot k_2 \cdot GM_2} = \frac{R_{20}}{k_{sense2} \cdot k_2} = f_2(k_2)$$

The second conduction current  $I_2$  can thus be set by means of the second transistor T3. The second transistor T3 can be set in turn by means of the programmable second transmission function  $k_2$  of the digital filter 4. The ringing impedance thus depends on the programmable second transmission function  $k_2$  of the digital filter 4 and can be adapted to various specific requirements for particular countries by simply reprogramming the second transmission function  $k_2$  of the digital filter 4. The reprogramming of the second transmission function  $k_2$  is carried out here in a way analogous to the reprogramming of the first transmission function  $k_1$ .

The first transmission function  $k_1$  and the second transmission function  $k_2$  are preferably identical, so that the same ringing impedance  $Z_{total}$  is respectively set for either a positive or negative half-wave of the ringing alternating voltage  $V_{\sim}$ . This presumes, of course, identical conductance values  $GM_1$  and  $GM_2$  of the first analog integrator circuit 8' and second analog integrator circuit 8'' and identical voltage divider ratios of the first and second voltage dividers. Thus, with  $GM_1 = GM_2$  and  $k_{sense1} = k_{sense2}$ , the ringing impedance  $Z_{total}$  obtained is:

$$Z_{total} = Z_1 = Z_2.$$

However, with the circuit arrangement according to the invention, it is also possible to set an asymmetrical ringing impedance which has a different ringing impedance  $Z_1$  for the positive half-wave of the ringing

1. *What is the purpose of the study?*  
 2. *What are the research questions or hypotheses?*  
 3. *What is the study design?*  
 4. *What is the sample size and how was it selected?*  
 5. *What are the variables being studied?*  
 6. *What are the data collection methods?*  
 7. *What are the results of the study?*  
 8. *What are the conclusions and implications of the study?*